

An Introduction to Krill Herd Algorithm

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Introduction



- A single provisional solution
- Iteratively **improved** until a stagnation point in the same area of the initial solution is reached
- Examples:
 - Simulated Annealing, Tabu Search, Variable Neighborhood Search, and Hill Climbing.

Introduction



- A set of random individual
- Iteratively recombine the solutions and follow the survival of the fittest principle until the acceptable solution is reached
- Examples:

Genetic Algorithm, Harmony Search Algorithm, Genetic Programming.

Introduction



- A set of points
- The solutions are normally **constructed** based on **historical information** gained by **previous** generations
- Examples:
 - Artificial Bee Colony Algorithm, Bacterial Foraging Algorithm, Biogeographical-based Optimization, Cuckoo Search Algorithm, and Firefly Algorithm

General Structure of KH Algorithm

- Motion Induced Process
- Foraging Movement
- Random Physical Diffusion
- Position Update

Crossover

Mutation



General Structure of KH Algorithm

- * It is a swarm intelligence search algorithm that is motivated based on the herding behavior of krill individuals.
- The objective function for the movement of krill is measured by the shortest distance of each individual krill from food and highest density of the herd.
- Each individual in KH algorithm modifies its position based on three operational process: (1) motion induced by other individuals (2) foraging movement and (3) random physical diffusion.
- The KH algorithm is being referred to as a powerful search technique because it contains both exploration and exploitation strategies based on foraging movement and the motion induced by other individuals respectively.
- As a swarm intelligence technique with a lot of advantages, it combines the efficient operations of evolutionary-based algorithm utilizing crossover and mutation components within its framework and thus makes the search framework stronger.

Krill Herd Algorithm



Motion Induced Process

The velocity of individual Krill is influenced by the movement of other Krill in the multi-dimensional search space where its velocity is dynamically perturbed based on local effect, target swarm effect and repulsive swarm effect.

$$\theta_{i}^{new} = \epsilon_{i}\theta_{i}^{max} + \mu_{n}\theta_{i}^{old}$$
where
$$\epsilon_{i} = \epsilon_{i}^{local} + \epsilon_{i}^{target}$$

$$\epsilon_{i}^{local} = \sum_{i=0}^{Ns-1} f_{ij}x_{ij}$$
Note that
$$f_{ij} = \frac{f_{i} - f_{j}}{f_{w} - f_{b}}$$

$$x_{ij} = \frac{x_{i} - x_{j}}{|x_{i} - x_{j}|rand(0, 1)}$$

$$\epsilon_i^{target} = 2\left(rand(0, 1) + \frac{i}{i_{max}}\right) f_i^{best} x_i^{best}$$

Motion Induced Process



(7)

Foraging Movement

The foraging movement of each individual krill is formulated in terms of the current food location and the previous knowledge about the food location.

 $F_m = V_f a_i + \mu_f F_m^{old}$ where $a_i = a_i^{food} + a_i^{best}$

- $F_m \rightarrow$ The first movement
- $V_f \rightarrow$ The foraging velocity
- $\mu_f \rightarrow$ The inertia weight of the foraging movement in (0,1)
- $F_m^{old} \rightarrow$ The previous foraging movement
- $a_i^{best} \rightarrow$ The food attractive
- $a_i^{food} \rightarrow$ the effect of the best fitness of the each individual krill

Random Physical Diffusion

In KH algorithm, the population diversity is enhanced with the aid of random diffusion process that is integrated in krill individuals. The mathematical expression of the random diffusion process in terms of a maximum diffusion speed and a random directional factor that follows:

 $RD_i = RD^{\max}\vartheta$



Position Update: Crossover - Mutation

Crossover:

In this phase, each member of krill update its current position using the position of others in accordance with the position update equation.

$$x_{ij} = \begin{cases} x_{rj} & \text{if } rand(0,1) < C_{R_i} \\ & \text{where } r = 1, 2, \dots, n_p; r \neq i \\ & x_{ij} & \text{otherwise} \end{cases}$$

 $C_{R_i} = 0.2 f_i^{best}$

Mutation:

 $M_R = \frac{0.05}{E^{BEST}}$

The usage of the mutation operator is determined by a mutation rate parameter (M_R). The mutant solutions X_{ij} changing the solution X_{best_j} with the difference of two other randomly selected vectors X_{nj} and X_{pj}

$$x_{ij}^{mutant} = x_{BESTj} + M_R(x_{nj} - x_{pj})$$

$$x_{ij}^{\text{mod}} = \begin{cases} x_{ij}^{\text{mutant}} & \text{if } rand(0, 1) \le M_R \\ x_{ij} & \text{otherwise} \end{cases}$$

Basic krill-Inspired Algorithm

1:	Initialization of Krill parameters: V_f , RD ^{max} , θ^{max} , C_R , M_R , and n_p .
2:	for $j - 1$ to n_p do
3:	for i - 1 to d do
4:	$x_{ij} - LB_i + (UB_i - LB_i) \times U(1, d)$ {Initialization of krill population}
5:	end for
6:	Compute <i>f</i> _i {Evaluate each krill}
7:	end for
8:	Sort the krill and find x^{best} , where $best \in (1, 2,, n_p)$
9:	while t < Max_i terations do
10:	for $j - 1$ to n_p do
11:	Perform the three motion calculation using Eqs (1), (8) and (10)
12:	$x_i(t + \delta t) = x_i(t) + \delta t \frac{dx_j}{dt}$ {Update each krill}
13:	Fine-tune x _{i+1} by using krill operators: Crossover and mutation
14:	Evaluate each krill by x _{i+1}
15:	end for
16:	Replace the worst krill with the best krill.
17:	Sort the krill and find x^{best} , where $best \in (1, 2,, n_p)$
18:	t-t+1
19:	end while
20:	Return x ^{best}



Did You Know ?

- The KH algorithm can be used for the training artificial neural networks.
- The emergence of artificial neural networks as an important tool in the domain of artificial intelligence and optimization could not be over emphasized.
- Using KH algorithm, it can be concluded that it produces promising results in terms of classification error (CE), sum of square errors (SSE) and time taken for the training of the ANN.



- Binary-Based KH Algorithm
- Chaotic-Based KH Algorithm
- Fussy-Based KH Algorithm
- Discrete-Based KH Algorithm
- Opposition-Based KH Algorithm





- ✤ The krill individuals are position to the **binary coordinates**.
- The proposed technique outperforms three other approaches when evaluated on several feature selection datasets.





- The various chaotic maps are utilized to change the three main movements of the KH algorithm during the search process.
- ✤ It is found that modified KH algorithm **performs** better than the classical KH algorithm.



- The **performance** of the KH algorithm could be more powerful, if it is integrated with **fuzzy sets theory**.
- Proposed fuzzy-based KH algorithm where fuzzy system is utilized to finetune the parameters during the search cycle to strike a **balance** between the **exploration** and **exploitation** capabilities while solving the problems.



- The continuous nature of the algorithm was modified to cope with the optimization problems of discrete variables.
- The performance of the KH algorithm is better when it comes to **decision making** and **path planning** for graphbased **network** and other discrete event based optimization problems.
- The flexible job-shop scheduling problem (FJSSP) is solved with discrete KH method where some heuristic strategies are incorporated in order to develop an effective solution approach.
- It also introduced elitism strategy into their proposed method to drive the krill swarm towards the better solutions during the search.



- The introduction of opposition based learning (OBL) strategy and free search operator into the KH algorithm (FSKH), each krill member can explore the space based on its own perception and scope of activities.
- The usage of free search strategy is to aid the individuals from being trapped in local optima, assists in the improvement of exploration capability and the diversity of the krill population. Thus, the modification aided the FSKH to strike a right balance between local exploitation and global exploration.

Hybridization of Krill Herd Algorithm

- Hybridization With Local-Based Search Algorithm
- Hybridization With Population-Based Algorithm



Hybridization with Local-Based Search Algorithm

- The population-based approaches likes KH algorithm are strong in the scanning the search space of multiple regions at the same time. However, it is not that efficient in navigating each region deeply.
- Local search-based algorithm is very efficient in deeply navigating a single search space region but cannot scan the whole search space regions.
- The hybridization of local search within the population search algorithm is very promising to complement the advantages of both types in a single optimization algorithm.
- The main aim of this type of hybridization is to strike the right balance between a wide range exploration and nearby exploitation of the problem search space.

Hybridization with Population-Based Algorithm

- The hybridization of KH algorithm with operators of other population-based algorithms in order to improve its performance when utilized for complex optimization problems.
- For example combining the exploitation of the employed bee component from global best artificial bee colony (GABC) with the exploration capability of the KH algorithm in order to generate the good solutions during the search process. the hybrid algorithm significantly performs better than the basic KH algorithm for all problems.
- The performance of the KH algorithm for solving global optimization is recently improved with harmony search (HS) in, where the HS is employed instead of physical diffusion to alter krill movement during the process of krill updating in the KH algorithm.
- It is worthy to mention that the proposed hybrid method effectively combined the global exploration of the HS with the local exploitation of the KH algorithm.

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Thanks for your kind attention!



